Numerical and Geometric Optimization Techniques for Environmental Prediction Systems



Hellenic Naval Academy Section of Mathematics

Introduction

Numerical environmental modeling is keeping the last decades a primary role in research and technological advances. The application of atmospheric and wave model Numerical wave (and atmospheric) models have been proved successful for the simulation of the general sea outputs for renewable energy estimation and monitoring is particularly highlighted under the concerns posed by the recent economic crisis and the questions for global global or intermediate scale. warming and climate change. Within this framework the utilization of optimization techniques which, in conjunction with mesoscale and regional wind/wave However, when focusing on local characteristics systematic errors may appear due to: modeling systems, provide accurate environmental predictions in long and short term horizons is receiving increased attention.

In the present work, novel techniques for the estimation of the biases and uncertainty of numerical weather prediction systems are proposed based on the combination the inability to capture sub-scale phenomena of dynamical statistical tools (Kalman filters) and recent advances in a relatively new branch of mathematics the Information Geometry. The latter implements the parameterization of certain atmospheric/wave procedures techniques from the non-Euclidean geometry in statistics, targeting to the optimization of the solution of nonlinear problems. More precisely, the probability distributions obtained by simulated wind/wave data and the corresponding observations are categorized as elements of statistical manifolds, the appropriate geometric the lack of a dense observation network which could help on the systematic correction of initial cond framework is clarified – avoiding classical simplifications associated with least square methods, and the discrepancies between the modeled and recorded datasets are Ways out - Optimizing the Numerical Models Outputs measured by means of corresponding minimum length curves (geodesics). The latter are reached as solutions of second order differential equations for the study of Increase the model resolution: It remains an open question if this leads to a considerable improvement of the which numerical techniques are employed. The proposed methodology is applied to selected areas of Greece targeting to the optimal estimation and monitoring of if this is true, it also results to increased computational cost. renewable energy sources.

Numerical Modeling for Wind/Wave Parameters

The validity for high quality wind/wave simulations is of critical importance today for a number of important applications:

| ✓ Global Warming | \checkmark Marine pollution |
|--|---|
| \checkmark Renewable energy estimation, monitoring and forecasting | ✓ Ship safety |
| ✓ Transportation | ✓ Agricultural activities |

The use of numerical prediction models, in combination with available observations, has been recognized by the research and technical community as the main tool towards accurate environmental simulations/forecasts. Such models solve the main equations governing the atmosphere and wave evolution based on arithmetic schemes (finite differences on grid points or others).

The following models are utilized by our group for atmospheric and wave simulations

Wave Model WAM

WAM - ECMWF parallel version (Komen et al., 1994; WAMDI group, 1988; Bidlot J. and Janssen P. 2003) is a third generation wave model, which computes spectra of random short-crested wind-generated waves.

- The model describes the evolution of a two-dimensional ocean wave spectrum.
- In contrast to first and second generation models, WAM introduces no ad hoc assumptions on the spectral shape.
- It computes the 2-d wave variance spectrum through integration of the transport equation

$$\frac{dF}{dt} + \frac{\partial}{\partial \phi} (\dot{\phi}F) + \frac{\partial}{\partial \lambda} (\dot{\lambda}F) + \frac{\partial}{\partial \theta} (\dot{\theta}F) = S,$$

F represents the spectral density with respect to (f,θ,ϕ,λ) , f denotes frequencies, θ directions, ϕ latitudes, λ longitudes

The source function S is represented as a superposition of the wind input Sin, white capping dissipation *Sdis*, and nonlinear transfer *Snl*

Atmospheric Model SKIRON

SKIRON has been developed at the University of Athens by the Atmospheric Modeling and Weather Forecasting Group based on the Eta/NCEP model

- It consists of various modules for pre- and post- processing together with a version of the Eta model appropriately coded in order to run on any parallel computer platform
- Is a full physics non-hydrostatic model with sophisticated convective, turbulence and surface energy budget scheme

Atmospheric Model RAMS

RAMS is a highly versatile numerical code, developed at Colorado State University and Mission Research Inc/ASTeR Division. It is considered as one of the most advanced modeling systems available today.

It is a merger of a non-hydrostatic cloud model and a hydrostatic mesoscale model. It is able to simulate atmospheric phenomena with resolution ranging from tens of kilometers to a few meters.

George Galanis^{1,3}, Ioannis Famelis², Christina Kalogeri^{1,3} and George Kallos³

¹Hellenic Naval Academy, Section of Mathematics, Xatzikyriakion, Piraeus 18539, Greece ² Technological Educational Institution of Athens, School of Technological Applications, Egaleo, Athens11210, Greece ³ University of Athens, Department of Physics, Atmospheric Modeling and Weather Forecasting Group, University Campus, Bldg. PHYS-V, Athens 15784, Greece

Models Limitations

- the strong dependence on the initial/boundary conditions,

Assimilation systems.

- Used for correcting the initial conditions based on available observations
- Problems: Limited available/quality controlled observations over oceans, Limited spatial and temporal in

Statistical post-processing methods for local adaptation

MOS methods, Neural networks:, Kalman filters

In all the above cases *a cost function should be minimized*

For example, in the case of Kalman filters :

The evolution in time of an unknown process \mathbf{x}_t is described by the system equation: $\mathbf{x}_t = \mathbf{F}_t \cdot \mathbf{x}_{t-1} + \mathbf{w}_t$

A known process \mathbf{y}_t is used in connection with \mathbf{x}_t by the observation equation $\mathbf{y}_t = \mathbf{H}_t \cdot \mathbf{x}_t + \mathbf{v}_t$

The filter is based on the minimization of the covariance matrix $E(x_t x_t^T)$ of x_t

Is this distance adequately measured?

A serious simplification is made here: The distance/cost-function is measured by means of classical Euclidean

Information Geometry

Information geometry is a relatively new branch of Mathematics applying methods and techniques of no stochastic processes.

- A main subject: Given two probability distributions or two data sets, is it possible to define a notion of *distance* between them?
- Families of probability distributions are recognized as (statistical) manifolds on which geometrical entities such as Riemannian metrics, can be naturally introduced.
- The geometrical framework in such a manifold is given by the *Fisher information matrix* with elements

 $g_{ij}(\xi) = \int \partial_i \ell(x;\xi) \partial_j \ell(x;\xi) p(x;\xi) dx$

where $\ell(x;\xi) = log[p(x;\xi)]$ and p the distributions

The minimum distance between two statistical manifold is defined by the the minimum length curve ω that con $\omega = (\omega_i) : \mathbb{R} \to S$ is the solution differential equations:

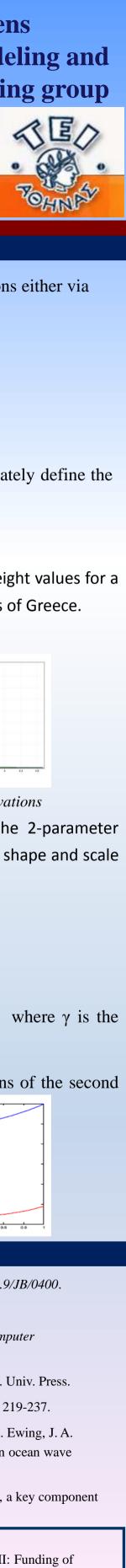
$$\omega_i^{\prime\prime}(t) + \sum_{j,k=1}^n \Gamma_{jk}^i(t) \,\omega_j^\prime(t) \omega_k^\prime(t) =$$

under the conditions $\omega(0) = f_1$, $\omega(1)$ are the <u>Christoffel symbols</u> of the <u>Lev</u> respect to the Fisher metric



University of Athens Atmospheric Modeling and Weather Forecasting group

Technological Educational Institute of Athens



| | Applications of Information Geometry to Wind/Wave Modeling | |
|---|--|--|
| state conditions on | Information Geometric techniques can significantly support the optimization of the environmental predictions eit assimilation or post process systems. | |
| | The main steps that should be taken are: | |
| | • Estimate the statistical distributions followed by the data in study. | |
| | • Establish the corresponding geometric environment, i.e. the appropriate statistical manifold. | |
| | • Use this framework in order to accurately estimate the distance between data sets and, therefore, adequately | |
| | cost-functions used. | |
| ditions. | A test case for area of Greece | |
| he forecast skill. Even | The numerical models SKIRON and WAM were used to numerically wind speed and significant wave height v 10-year period (2001 – 2012) at a high spatial (5Km) and temporal resolution mode over different areas of Gr | |
| | The results were compared with corresponding records from satellites. | |
| impact | Protect Audio Protect Audio Protec | |
| | The testing area The modeled data The corresponding observations | |
| | Based on different statistical tests (Kolmogorov-Smirnov, Anderson-Darling) it was proved that the 2- Weibull distribution fits well to the data in study, both modeled and observed data, but with different shape parameters (a, β). | |
| | The obtained pdfs could be recognized as elements of the Weibull statistical manifold: | |
| | $S = \left\{ f(x) = \frac{\alpha}{\beta} \left(\frac{x}{\beta} \right)^{\alpha - 1} e^{-\left(\frac{x}{\beta}\right)^{\alpha}}, \ \alpha, \beta > 0 \right\}$ | |
| | • The Fisher information matrix takes the form $G(\alpha,\beta) = \begin{bmatrix} \alpha^2 \beta^2 & \beta(1-\gamma) \\ \beta(1-\gamma) & \frac{6(\gamma-1)^2 + \pi^2}{6\alpha^2} \end{bmatrix} = \begin{bmatrix} 5.76 & 0.63 \\ 0.63 & 0.71 \end{bmatrix}$, whe Euler Gamma. | |
| | The corresponding geodesics, necessary to estimate distances between different data sets are solutions of order system: | |
| an Geometry tools. | $\omega_1'' - 0.94(\omega_1')^2 + 1.39\omega_1'\omega_2' - 0.17(\omega_2')^2 = 0$ | |
| on-Euclidean geometry to | $\omega_{2}'' - 0.18 (\omega_{1}')^{2} + 0.55 \omega_{1}' \omega_{2}' - 0.69 (\omega_{2}')^{2} = 0$ | |
| | • Numerical techniques should be utilized for solving such type of equations | |
| b elements f_1 and f_2 of a | References | |
| e corresponding geodesic - | Bidlot J. and Janssen P. 2003: Unresolved bathymetry, neutral winds and new stress tables in WAM. ECMWF Research Department Memo R60.9/JB/04 | |
| nnects them. Such a curve | Holthuijsen, Leo H. Waves in Oceanic and Coastal Waters. Cambridge University Press, 2007 | |
| of a system of 2 nd order | Kallos G., 1997: The Regional weather forecasting system SKIRON. Proceedings, <i>Symposium on Regional Weather Prediction on Parallel Computer Environments</i> , 15-17 October 1997, Athens, Greece, 9 pp. | |
| $i = 0, i = 1, 2, \dots, n.$ | Komen G., Cavaleri L., Donelan M., Hasselmann K., Hasselmann S., Janssen P.A.E.M., 1994: <i>Dynamics and Modelling of ocean waves</i> , Camb. Univ. Papadopoulos A., P. Katsafados, and G. Kallos, 2001: Regional weather forecasting for marine application. <i>Global Atmos. Ocean Syst.</i> , 8 (2-3), 219-23 WAMDIG: The WAM-Development and Implementation Group,1988: S.Hasselmann, K. Hasselmann,E. Bauer, L. Bertotti, C. V. Cardone, J. A. Ewing Greenwood, A. Guillaume, P. A. E. M. Janssen, G. J. Komen, P. Lionello, M. Reistad, and L. Zambresky: The WAM Model - a third generation ocean | |
| 1) = f_2 , where $\left(\Gamma_{jk}^i\right)$ | prediction model, J. Phys. Oceanogr., Vol. 18, No. 12, pp, 1775 - 1810. Zodiatis G., Lardner R., Georgiou G., Demirov E., Pinardi N., Manzella G. (2003). The Cyprus coastal ocean forecasting and observing system, a key of | |
| evi-Civita connection with | in the growing network of European ocean observing systems, Sea Technology, v.44, n.10, 10-15. | |
| | Acknowledgments: This work is co-funded by the European Union (European Social Fund) and Greek national resources under the framework of the "Archimedes III: Fund Research Groups in TEI of Athens" project of the "Education & Lifelong Learning" Operational Programme. | |